

# Black-Box Optimisation Techniques for Complex Systems

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Lindon Roberts, University of Sydney ([lindon.roberts@sydney.edu.au](mailto:lindon.roberts@sydney.edu.au))

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1. **Black-Box Optimisation**
2. Overview of optimisation techniques
3. Example application (imaging)
4. Advice

# Black-Box Optimisation

A general optimisation problem looks like:

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Ubiquitous in academic research & industrial problems: maximise revenue, minimise risk, maximise design efficiency, minimise prediction errors, ...

# Black-Box Optimisation

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- Legacy/proprietary code is involved in a computation
- Any sufficiently complex calculation/simulation can effectively be a black-box (“I don’t have time to figure this out!”)



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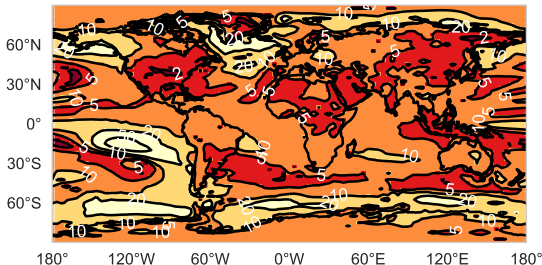
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Black-box optimisation = optimisation when at least one objective/constraint function is a black box.

## Application 1: Climate Modelling

[Tett et al., 2022]

- Parameter calibration for global climate models (least squares minimisation)
- One model run = simulate global climate for 5 years (expensive!)
- Very complicated, chaotic physics (black-box & noisy!)



## Application 2: Adversarial Example Generation

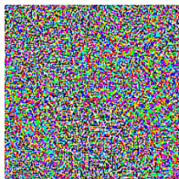
[Alzantot et al., 2019]

- Find perturbations of neural network inputs which are misclassified (min. probability of correct label/max. probability of desired incorrect label)
- Neural network structure assumed to be unknown (black-box!)
- Want to test very few examples ( $\approx$  expensive!)



“panda”  
57.7% confidence

+ .007 ×



=



“gibbon”  
99.3 % confidence

## Issue?

### Why is black-box optimisation hard?

Generally two reasons black-box optimisation may be difficult:

- Evaluating the BB functions may be very slow/costly or inaccurate
- Don't have access to derivatives of BB functions (and hard to estimate)
  - Some recent work considers only *comparison oracles*: given  $x$  and  $y$ , say which is better (but no values of  $f$ ), e.g. survey results [Slavin & McKenzie, 2022]

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Most standard optimisation techniques assume availability of derivatives of objective and all constraint functions, and will evaluate functions at many points to achieve high-quality solutions.

1. Black-Box Optimisation
2. **Overview of optimisation techniques**
3. Example applications (imaging)
4. Advice

# Overview of Techniques

For simplicity, focus on methods for unconstrained or box-constrained problems.

Other constrained problems usually solved with modifications of these underlying techniques.

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Other constrained problems usually solved with modifications of these underlying techniques.

Important distinction: **local** or **global** optimisation?

- Local: best  $x$  amongst nearby points
  - Faster, more theoretical guarantees.
  - Better when many decision variables.
- Global: best  $x$  in entire feasible region
  - Can find better points, but usually slower.
  - Only theory is “works if you eventually search everywhere”.
  - Algorithms balance “exploration” (search new areas) with “exploitation” (zoom in on known good regions).



## Very successful framework: model-based methods

- Evaluate  $f$  at an initial collection of points
- Build an approximation to  $f$  (e.g. interpolation). Can be **local** or **global** models (region of accuracy)
- Minimise approximation to select a new point to evaluate
  - If global, sometimes consider far away points instead (exploration)
- Evaluate new point and update model

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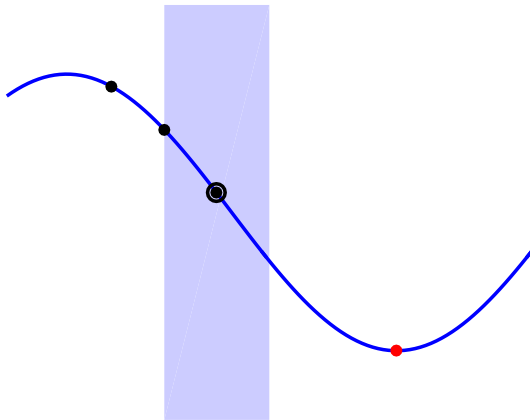
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Comes in local (model-based derivative-free optimisation) and global (surrogate/Bayesian optimisation) flavours.

**I have several open-source Python software packages of this type!**

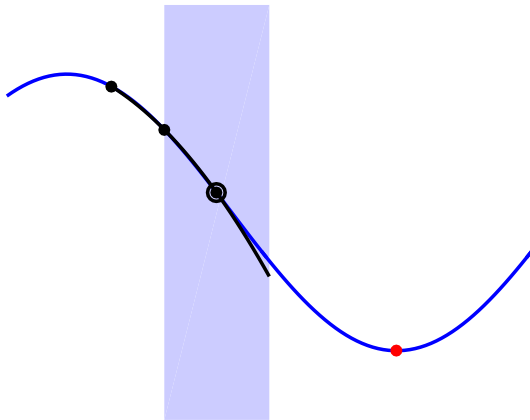
[Conn, Scheinberg & Vicente, 2009; Shahriari et al., 2016]

## Example: Model-Based DFO



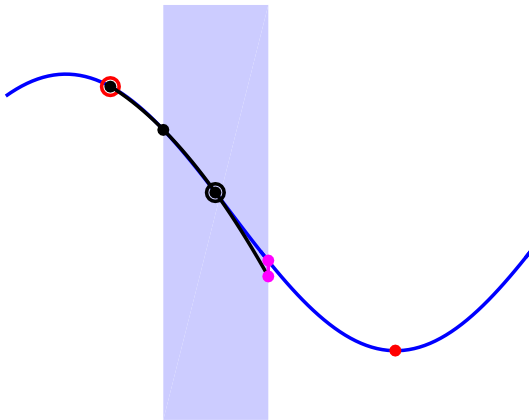
### 1. Choose interpolation set

## Example: Model-Based DFO



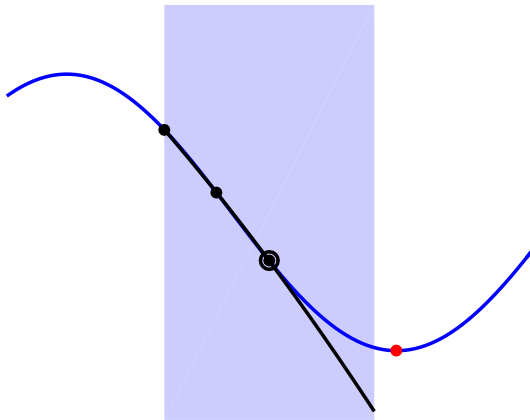
### 2. Interpolate & minimize...

## Example: Model-Based DFO



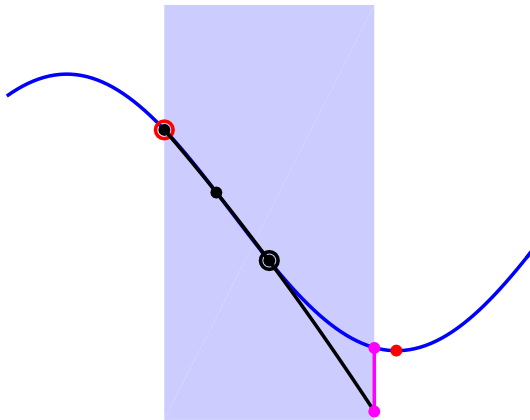
### 3. Add new point to interpolation set (replace a bad point)

## Example: Model-Based DFO



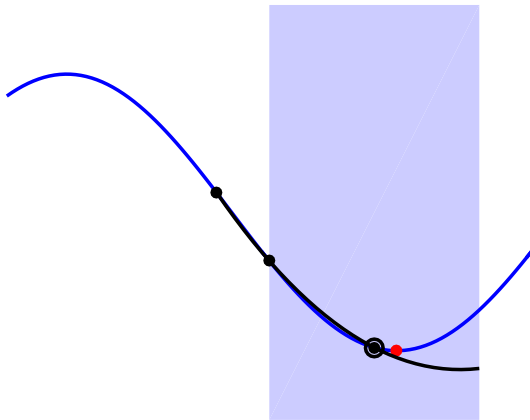
**4. Repeat with new interpolation set & model**

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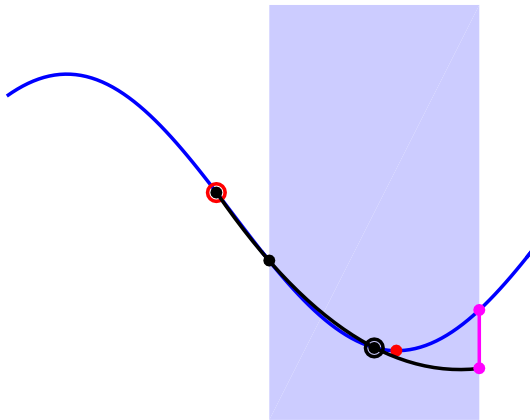
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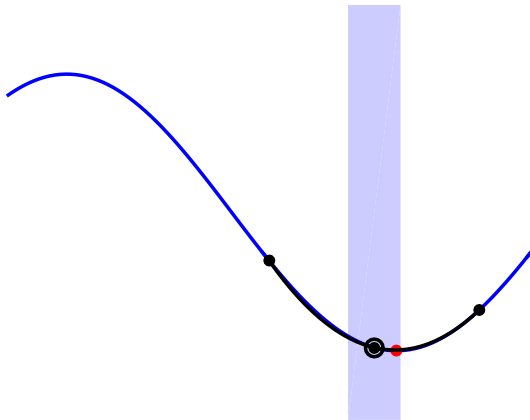


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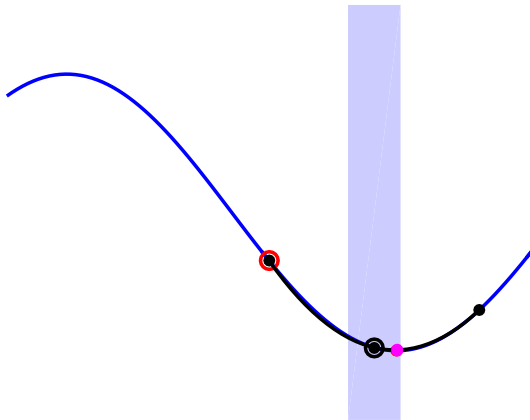
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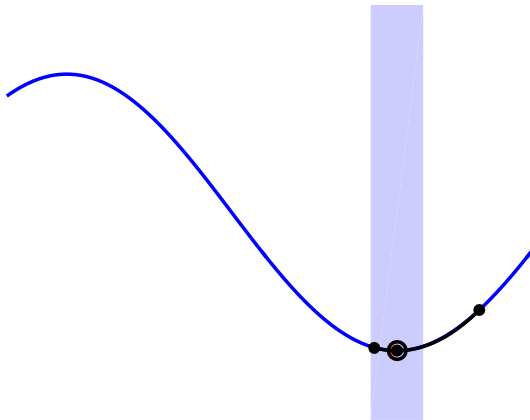
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## Global method: DIRECT (Dlviding RECTangles)

- Start with one rectangle: the feasible box region (constraints assumed)
- Evaluate  $f$  in the centre of all rectangles
- Pick rectangle(s) which are large and/or have small centre  $f$
- Subdivide these rectangles into thirds to get new rectangles

Rapidly gained popularity and many modifications proposed to improve performance.

[Jones, Perttunen & Stuckman, 1993]

# Example: DIRECT

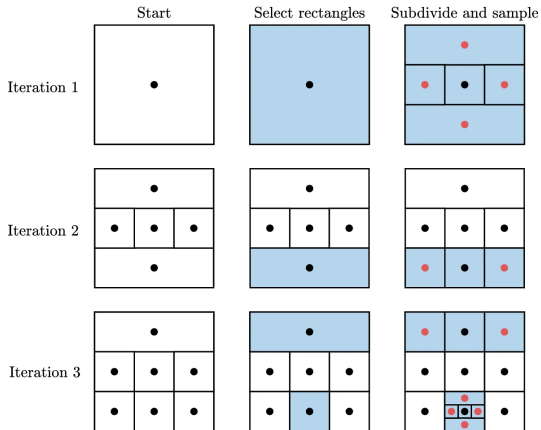


Image from [Jones & Martins, 2021]

## Other Methods

Many other methods not discussed here, such as

- Nelder-Mead simplex method (local)
- Direct search (local)
- Simulated annealing (global)
- Genetic/evolutionary algorithms (global)
- Particle swarm (global)

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Nelder-Mead very popular because of its simplicity, not so good in practice. Direct search mostly works well if augmented with model-based ideas, but simple/flexible.

Global methods ‘inspired by nature’ tend not to perform as well as ‘inspired by mathematics’ (but quite general, best as fallback option).

*“Methods inspired by nature are for the ignorant or the desperate.” — A. R. Conn, 2018.*

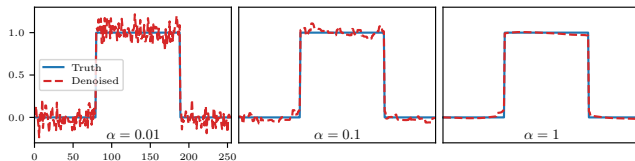


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# Inverse Problems

A common inverse problem is to match some observed data, encouraging solutions of a particular sort with a regulariser.

e.g. Image denoising: given a noisy image  $y$ , find a denoised image  $\hat{x}$  by minimising  $\text{error}(\hat{x}, y) + \alpha \text{variation}(\hat{x})$ . The solution depends on the choice of  $\alpha$ .



## How to choose good problem parameters?

Learn from data! Given  $(x_1, y_1), \dots, (x_n, y_n)$  — ground truth and noisy observations, find  $\alpha$  which minimises average error  $\text{error}(\hat{x}_i(\alpha), x_i)$ . Treat  $\hat{x}_i(\alpha)$  as black box!

# Results

Can learn parameters which give good denoising results:



**Takeaways:** black-box optimisation realistic (don't pretend you have derivatives you can't compute), faster results than assuming derivatives.

**Next step:** learn **sampling pattern for MRIs** (i.e. which Fourier coefficients to collect).

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## General Advice

My advice when doing optimisation on complex systems/black-box functions:

- Pick your variables, objective and constraints carefully — what do you actually want to solve?
- Understand the structure: discrete vs. continuous variables, linear vs. nonlinear constraints, special problem structure (e.g. least-squares)
- Local vs. global methods?
  - Local is faster, more scalable, better guarantees, better at exploiting good starting guesses & problem structure
  - Global can sometimes find better solutions
- Software? [Rios & Sahinidis, 2013; Cartis, R. & Sheridan-Methven, 2022]
  - Local: mine! (see my website)
  - Global: DIRECT or PySOT [Regis & Shoemaker, 2007]

## Key Message

Optimisation of complex, black-box systems is possible, but it takes a lot of work.

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## Conclusions

- Standard optimisation packages (SciPy, fmincon, ...) usually won't work well
- Alternative techniques exist and rapidly becoming more sophisticated
- Big ongoing research area: scalability (large numbers of decision variables, e.g. machine learning)

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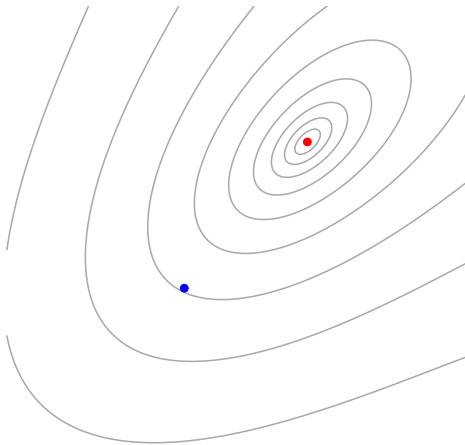
## Simple local method: direct search

- Look at fixed perturbations around best point so far (for a given step length)
- If some perturbation gives sufficient improvement:
  - Make perturbation new best point, increase step length
- Otherwise, keep old best point, decrease step length

Need perturbations to satisfy: for any fixed vector  $v$ , there is always a perturbation  $d$  making an acute angle with  $v$ . For example,  $\{\pm \text{coordinate directions}\}$ .

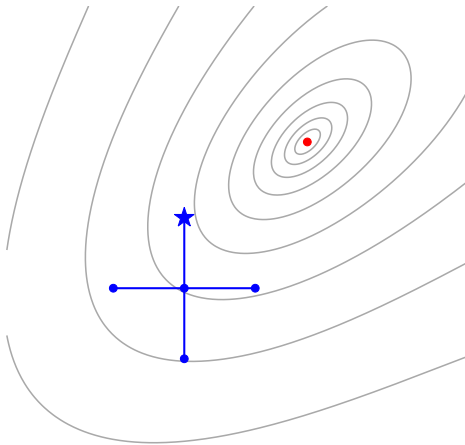
[Kolda, Lewis & Torczon, 2003; Conn, Scheinberg & Vicente, 2009]

## Example: Direct Search



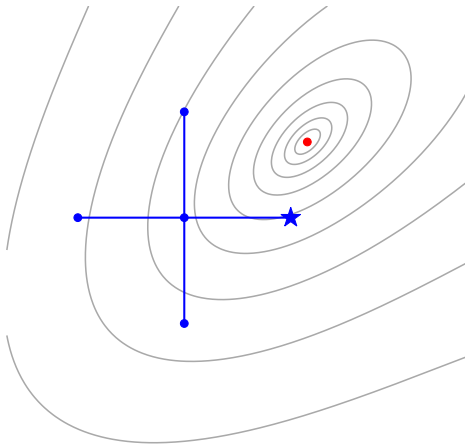
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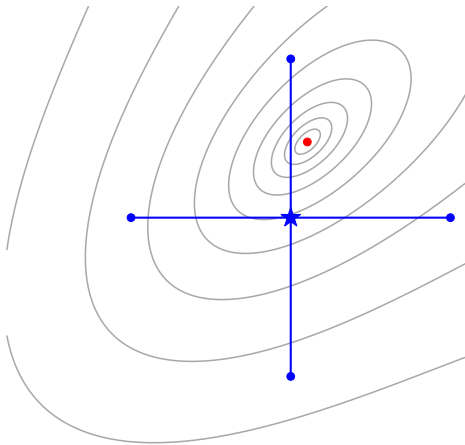
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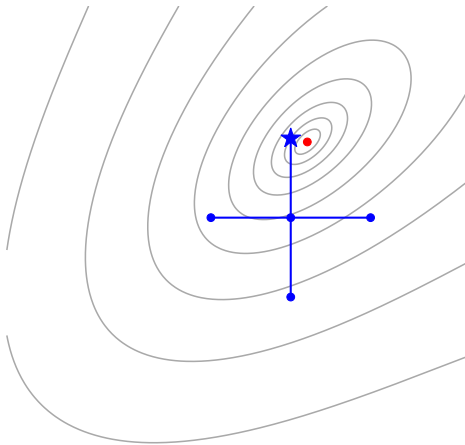
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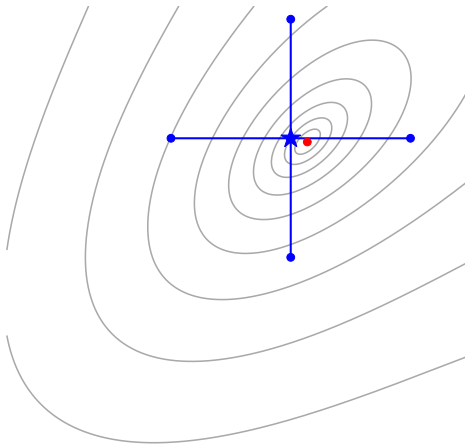
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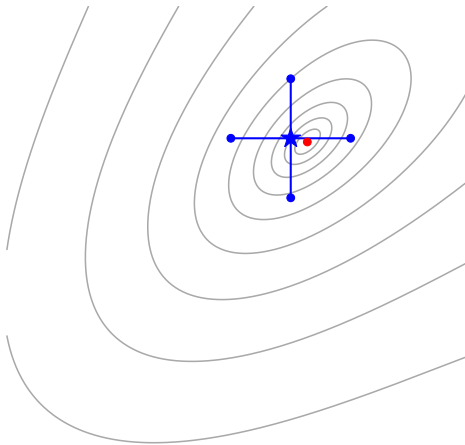
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